



\* Slip rate function is derived from the source time function with the rigidity model constructed for subfaults with different locations along dip direction, neglecting the finiteness of the subfault.

Asano and Iwata, 2012).

at deep side of the hypocenter (e.g.,

# **Abstract**

# The 2011 Ibaraki-Oki earthquake



# Relationship between the 2011 Tohoku earthquake and the 2011 Ibraki-Oki earthquake

We try to discuss the relationship between the mainshock and the Ibaraki-Oki event in the view points of aftershock occurrence between two events and the after-seismic slip.

## **Result & Discussion**

- Just before the 2011 Ibaraki-Oki earthquake (at 15:03:58 and at 15:07:16), two interplate earthquakes occurred in the northeastern part of the source area of the 2011 Ibaraki-Oki earthquake. Judging from the existence of these events, we can say that the source area of the 2011 Ibaraki-Oki earthquake does not overlap with the large coseismic slip area of the 2011 Tohoku earthquake because aftershocks would occur in the adjacent area to large coseismic slip area.
- Two large after-slip area can be shown and those large after-slip areas do not overlap large coseismic area of the two events. One is located at the deeper side of large coseismic area of the 2011 Tohoku earthquake and the other smaller area is located south side of the coseismic area of the 2011 Ibaraki-Oki earthquake which is found in PAC-PHS contact zone.

15:03:58 Tohoku–Oki

Ibaraki-Oki

Acknowledgement: The strong-motion data recorded by K-NET, KiK-net, and F-net of SI, the JMA unified hypocenter catalog, and the F-net CMT solution catalog were used for

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<sup>0.0 8.6 17.2 25.8 34.4 43.0</sup> 

# The 2011 Tohoku earthquake

## **Inversion Detail**

### Data

Teleseismic body waves

We use the vertical-component waveforms at 42 IRIS stations with epicentral distances in period of 10-100 s containing not only P-phase (where P-phase means direct P-wave and depth phases such as pP and sP) but also PP-phase in this study. The time length of the dataset in the source inversion is 300 s (starting 10 s before the

P-wave arrival).

Terrestrial GPS data

We use three components of static displacements at 351 GEONET stations. The static displacements of this event were obtained by differencing its preseismic and postseismic positions.

Seafloor crustal deformation data

We use three components of five seafloor static displacements (Sato et al., 2011). Green's function

Teleseismic Green's function

P and PP theoretical waveforms are calculated after Kikuchi and Kanamori (2003) with six one-dimensional velocity structure models for subfaults with different locations along the dip direction referring to Miura et al. (2005). Theoretical P and PP phase onsets are set to observed ones for each station. Geodetic Green's function

Theoretical static displacements were calculated assuming a homogeneous elastic halfspace after Okada (1992). Method

We use the kinematic linear waveform inversion with multiple time windows (Hartzell and Heaton, 1983). The slip time history of each subfault is represented by the superposition of 24 time windows with 8.0 s width, each of which is put with 4.0 s lag. The maximum slip duration at each subfault (Tsd) of 100 s was determined by semblance analysis of the near-source small-aperture seismic array data of the strong ground motion waveforms to estimate the wave-radiation duration from the area around the hypocenter. We assume a realistic curved fault surface model considering the three-dimensional shape of the plate boundary (Miura et al., 2005; Nakajima and Hasegawa, 2006; Nakajima et al., 2009; Kita et al., 2010). Relative weights among different kinds of data-set were determined by theoretical tests. The propagation velocity of the first time window (Vftw) of 2.0 km/s was determined by the matching of the slip patterns of the teleseismic model and the geodetic model.

## Data Fitting

The fitting in both of the teleseismic and geodetic data is quite well. The variance reductions of the teleseismic data and the geodetic data are 67.2% and 99.4%, respectively.

Comparison of the observed (red) and synthetic (black) teleseismic body waveforms

man? MMM ~ ~ Mmm ~ MMmm mmmi ~mmmi ~mmmi ~mmmi ~mmmi  $-M_{m}^{33} - M_{m}^{127} - M_{m}^{230} - M_{m}^{335}$  $-M^{258} - M^{42} - M^{42} - M^{42} - M^{258} - M^{339}$  $\mathcal{W}_{45}^{42} = \mathcal{W}_{84}^{156} = \mathcal{W}_{51}^{298} = \mathcal{W}_{51}^{298}$  $M^{350} - M^{174} - M^{357} - M^{350}$  $M_{47}^{57} \rightarrow M_{47}^{176} \rightarrow M_{57}^{312} \rightarrow M_{47}^{312}$ Manna - Manny - Many -189



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Nakajima et al. (2009), J. Geophys. Res., 114, B08309. Okada (1992), Bull. Seismol. Soc. Am., 82, 1018-1040. Sato et al. (2011), Science, 332, 1395.

# The 2011 Ibaraki-Oki earthquake

## **Inversion Detail**

### Data

Strong-motion data

We use three components of time-series data from the 17 stations (K-NET, KiK-net, and F-net) in period of 5-50 s. The time length of the dataset in the source inversion is 50-80 s (starting 10 s before the S-wave arrival).

### GPS data

We use two horizontal components of static displacements at 83 GEONET stations. The static displacements of this event were obtained by differencing its preseismic and postseismic positions.

### Green's function

Strong-motion Green's function

Theoretical strong-motion waveforms were calculated using the discrete wavenumber method (Bouchon, 1981) and the reflection/transmission matrix method (Kennet and Kerry, 1979) using one-dimensional velocity structure models for each station referring Japan Integrated Velocity Structure Model Version 1 (Koketsu et al., 2012). Geodetic Green's function

Theoretical static displacements were calculated assuming a homogeneous elastic halfspace after Okada (1992). Method

We use the kinematic linear waveform inversion with multiple time windows (Hartzell and Heaton, 1983). The slip time history of each subfault is represented by the superposition of 7 time windows with 4.0 s width, each of which is put with 2.0 s lag. We assume a single planar fault model (120 km along strike × 120 km along dip) with a strike of 206° and a dip of 10° which refers to the spatial distribution of earthquakes deduced from ocean bottom seismographic observations (Yamada et al., 2011). In this study, the relative weights between different kinds of data-set and the relative weight of the smoothing constraint are determined by a trial-and-error process considering the fitting in each data and the agreement between the seismic moment estimated by this analysis and GCMT. The first time window triggering velocity (Vftw) of 2.2 km/s was selected so as to minimize the residual of strong-motion data fitting.

## Data Fitting

The fitting in both of the strong-motion and GPS data is quite well. The variance reduction of the strong-motion data and the GPS data are 84.4% and 97.4%, respectively.

## Comparison of the observed (red) and synthetic (black) strong-motion velocity waveforms



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Comparison of the observed (red) and